An Abductive Model for Human Reasoning

Steffen Hölldobler and Tobias Philipp and Christoph Wernhard

International Center for Computational Logic Technische Universität Dresden, 01062 Dresden, Germany sh@iccl.tu-dresden.de

Abstract

In this paper we contribute to bridging the gap between human reasoning as studied in Cognitive Science and commonsense reasoning based on formal logics and formal theories. In particular, the suppression task studied in Cognitive Science provides an interesting challenge problem for human reasoning based on logic. The work presented in the paper is founded on the recent approach by Stenning and van Lambalgen to model human reasoning by means of logic programs with a specific three-valued completion semantics and a semantic fixpoint operator that yields a least model, as well as abduction. Their approach has been subsequently made more precise and technically accurate by switching to three-valued Łukasiewicz logic. In this paper, we extend this refined approach by abduction. We show that the inclusion of abduction permits to adequately model additional empiric results reported from Cognitive Science. For the arising abductive reasoning tasks we give complexity results. Finally, we outline several open research issues that emerge from the application of logic to model human reasoning.

1 Introduction

In (McCarthy 1963) John McCarthy proposed a framework for reasoning about actions, causality, and causal laws, whose third postulate was that the formal descriptions of situations should correspond as closely as possible to what people may reasonably be presumed to know about them when deciding what to do. Human reasoning has been intensely studied within Cognitive Science (e.g. (Evans, Newstead, and Byrne 1993)) and there appears to be a widespread belief within the Cognitive Science community that logic is inadequate for human reasoning (e.g. (Byrne 1989)). Thus, an Artificial Intelligence approach to characterize commonsense reasoning using representations based on logic or other formal theories faces the formidable challenge of bridging the gap between human reasoning as studied within Cognitive Science and commonsense reasoning based on formal logics and formal theories.

Recently, in (Stenning and van Lambalgen 2008) Keith Stenning and Michiel van Lambalgen have proposed a twostage process to model human reasoning. Given a sentence in natural language, the first step consists of reasoning towards an appropriate logical representation, whereas in the second step conclusions are drawn with respect to the models of the generated logical representations. They propose to use logic programs, strong Kleene three-valued semantics with strong equivalence (Kleene 1952), a certain variant of completion semantics, a semantic fixpoint operator which yields a least model as well as abduction. Furthermore, they demonstrate the adequateness of their proposal by showing how the various scenarios considered in Byrne's suppression task (Byrne 1989) are adequately modeled.

However, the technical results of (Stenning and van Lambalgen 2008) contain an error, which was corrected in (Hölldobler and Ramli 2009b; 2009c) by considering the threevalued Łukasiewicz logic (Łukasiewicz 1920) instead of Kleene logic. But, the approach in (Hölldobler and Ramli 2009b; 2009c) does not include abduction and, hence, some scenarios of Byrne's suppression task are not yet covered. In this paper we close this gap by adding abduction to the approach in (Hölldobler and Ramli 2009b; 2009c).

The paper is organized as follows: In Section 2 we will briefly present the suppression task as a challenge problem for human reasoning based on logic. In Section 3 we review the approach presented in (Stenning and van Lambalgen 2008) with the modifications discussed in (Hölldobler and Ramli 2009b; 2009c). We extend this approach by abduction in Section 4. In Section 5 we demonstrate that the extended approach covers all scenarios of Byrne's suppression task and present further results. In the final Section 6 we discuss our findings and suggest some future research.

2 The Suppression Task

Ruth Byrne (Byrne 1989) has conducted a number of experiments where subjects (not trained in logic) were asked to draw various conclusions given certain sets of sentences. In order to compactly present the experiments we will make use of the abbreviations shown in Table 1. Furthermore, $\neg X$ shall denote the negative fact corresponding to the fact X, i.e. $\neg e$ denotes that *she does not have an essay to write*.

Table 2 summarizes the results reported in (Byrne 1989). E.g., the third experiment (in comparison to the first one) shows that the addition of the sentence C_o to C_e , e leads to the suppression of l, although l is still entailed by C_o , C_e , e in case of a (naive) representation of the sentences in classi-

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- C_e If she has an essay to write she will study late in the library.
- C_t If she has a textbook to read she will study late in the library.
- C_o If the library stays open she will study late in the library.
- e She has an essay to write.
- *l* She will study late in the library.
- o The library stays open.
- t She has textbooks to read.

Table 1: Some abbreviations.

K	Q	A	K	Q	A
C_e, e	l	96%	C_e, l	e	55%
C_e, C_t, e	l	96%	C_e, C_t, l	e	16%
C_e, C_o, e	l	38%	C_e, C_o, l	e	55%
$C_e, \neg e$	$\neg l$	46%	$C_e, \neg l$	$\neg e$	69%
$C_e, C_t, \neg e$	$\neg l$	4%	$C_e, C_t, \neg l$	$\neg e$	69%
$C_e, C_o, \neg e$	$\neg l$	63%	$C_e, C_o, \neg l$	$\neg e$	44%

Table 2: A brief summary of Ruth Byrne's experiments, where K denotes the given set of sentences, Q denotes the query and A denotes the percentage of positive answers.

cal propositional logic. The experiments have been repeated several times leading to similar figures (see e.g. (Dieussaert et al. 2000)).

3 A Logic for Human Reasoning

As mentioned in Section 1 the first step of the approach of (Stenning and van Lambalgen 2008) consists of reasoning towards an appropriate logical representation of the sentences. As this step is not under consideration in this paper, we simply repeat their proposal without further discussion.

Stenning and van Lambalgen consider logic programs, where the atoms occurring in the body of a clause can be either \top (denoting the truth value *true*), \perp (denoting the truth value *false*), or standard atoms. In particular, if A is an atom then $A \leftarrow \top$ denotes a *positive fact*, whereas $A \leftarrow \perp$ denotes a so-called *negative fact*. The latter becomes clear only if we apply a completion semantics (see below).

One of the main ideas in (Stenning and van Lambalgen 2008) is to represent conditionals by licences for conditionals using abnormality predicates. E.g., C_e , e is represented by the program

 $\mathcal{P}_{ee} = \{l \leftarrow e \land \neg ab, e \leftarrow \top, ab \leftarrow \bot\}.$ Likewise, C_e, C_t, e and C_e, C_o, e are represented by

$$\begin{array}{rcl} \mathcal{P}_{ete} &=& \{l \leftarrow e \wedge \neg ab_1, \ l \leftarrow t \wedge \neg ab_2, \ e \leftarrow \top, \\ & ab_1 \leftarrow \bot, \ ab_2 \leftarrow \bot \} \text{ and } \\ \mathcal{P}_{eoe} &=& \{l \leftarrow e \wedge \neg ab_1, \ l \leftarrow o \wedge \neg ab_2, \ e \leftarrow \top, \\ & ab_1 \leftarrow \neg o, \ ab_2 \leftarrow \neg e \}, \end{array}$$

respectively.

These programs are completed using a weak form of completion which is identical with Clark's completion (Clark 1978) except that undefined predicates stay undefined and are not declared to be false (see (Hölldobler and Ramli 2009b)). E.g., as the *weak completion* of the above mentioned programs we obtain:

$$\begin{array}{lll} wc \, \mathcal{P}_{ee} & = & \{l \leftrightarrow e \wedge \neg ab, \ e \leftrightarrow \top, \ ab \leftrightarrow \bot\}, \\ wc \, \mathcal{P}_{ete} & = & \{l \leftrightarrow (e \wedge \neg ab_1) \lor (t \wedge \neg ab_2), \ e \leftrightarrow \top, \\ & ab_1 \leftrightarrow \bot, \ ab_2 \leftrightarrow \bot\}, \\ wc \, \mathcal{P}_{eoe} & = & \{l \leftrightarrow (e \wedge \neg ab_1) \lor (o \wedge \neg ab_2), \ e \leftrightarrow \top, \\ & ab_1 \leftrightarrow \neg o, \ ab_2 \leftrightarrow \neg e\}. \end{array}$$

Programs and their (weak) completions are evaluated by three-valued interpretations. Such interpretations are represented by tuples of the form $\langle I^{\top}, I^{\perp} \rangle$, where I^{\top} and I^{\perp} denote the sets of all atoms which are mapped to *true* and *false*, respectively, $I^{\top} \cap I^{\perp} = \emptyset$, and all atoms which do not occur in $I^{\top} \cup I^{\perp}$ are mapped to *undefined* or *unknown*.

If we choose the three-valued Łukasiewicz semantics then programs enjoy the model intersection property, i.e., for each program, the intersection of all models is itself a model. Moreover, the model intersection property holds for weakly completed programs as well, and each model for the weak completion of a program is also a model for the program. See (Hölldobler and Ramli 2009b) for details. It should be noted that these properties do not hold if the strong Kleene semantics with complete equivalence is considered as done in (Stenning and van Lambalgen 2008).

The *least* model of a program is a model $\langle I^{\top}, I^{\perp} \rangle$ such that there does not exist another model $\langle J^{\top}, J^{\perp} \rangle$ with $J^{\top} \subset I^{\top}$ and $J^{\perp} \subseteq I^{\perp}$, or $J^{\top} \subseteq I^{\top}$ and $J^{\perp} \subset I^{\perp}$. It can be computed as the least fixed point of the following operator introduced in (Stenning and van Lambalgen 2008): Let *I* be an interpretation and \mathcal{P} a program. Then, $\Phi_{\mathcal{P}}^{SvL} = \langle J^{\top}, J^{\perp} \rangle$, where

$$J^{\top} = \{A \mid \text{there exists } A \leftarrow body \in \mathcal{P} \text{ with } I(body) = true\}, \\ J^{\perp} = \{A \mid \text{there exists } A \leftarrow body \in \mathcal{P} \text{ and } for all \ A \leftarrow body \in \mathcal{P} \text{ we find } I(body) = false\}.$$

One should observe the subtle difference in the first line of the definition of J^{\perp} if compared to the so-called *Fitting* operator usually associated with three-valued logic programs (see (Fitting 1985)).

As shown in (Hölldobler and Ramli 2009b; 2009c) the first six of Ruth Byrne's experiments (the first column in Table 2) are adequately modeled by considering the least model of corresponding weakly completed programs under Łukasiewicz semantics. For example, the least model of $wc \mathcal{P}_{eoe}$ is $\langle \{e\}, \{ab_2\} \rangle$ from which we conclude that it is *unknown* whether she studies late in the library. But what about the second column in Table 2? In order to model these experiments we need to add abduction.

4 Abduction

Let \mathcal{L} be a language, $\mathcal{K} \subseteq \mathcal{L}$ a set of formulas called *knowledge base*, $\mathcal{A} \subseteq \mathcal{L}$ a set of formulas called *abducibles* and $\models \subseteq 2^{\mathcal{L}} \times \mathcal{L}$ a logical *consequence relation*. Following (Kakas, Kowalski, and Toni 1993), the triple $\langle \mathcal{K}, \mathcal{A}, \models \rangle$ is called an *abductive framework*. An *observation* \mathcal{O} is a subset of \mathcal{L} ; it is *explained* by \mathcal{E} (or \mathcal{E} is an *explanation* for \mathcal{O}) iff $\mathcal{E} \subseteq \mathcal{A}, \mathcal{K} \cup \mathcal{E}$ is satisfiable, and $\mathcal{K} \cup \mathcal{E} \models L$ for each

 $L \in \mathcal{O}$. An explanation \mathcal{E} for \mathcal{O} is said to be *minimal* iff there is no explanation $\mathcal{E}' \subset \mathcal{E}$ for \mathcal{O} .

Here, we consider abductive frameworks that are instantiated in the following way: The knowledge base \mathcal{K} is a logic program \mathcal{P} , where \mathcal{L} is the language underlying \mathcal{P} . Let $\mathcal{R}_{\mathcal{P}}$ be the set of relation symbols occurring in \mathcal{P} , let

$$\mathcal{R}^{D}_{\mathcal{P}} = \{ A \in \mathcal{R}_{\mathcal{P}} \mid A \leftarrow body \in \mathcal{P} \}$$

be the set of *defined relation symbols* in \mathcal{P} and let $\mathcal{R}^U_{\mathcal{P}} = \mathcal{R}_{\mathcal{P}} \setminus \mathcal{R}^D_{\mathcal{P}}$ be the set of *undefined relation symbols* in \mathcal{P} . Then, the set of abducibles is

$$\mathcal{A} = \{ A \leftarrow \top \mid A \in \mathcal{R}^U_{\mathcal{P}} \} \cup \{ A \leftarrow \bot \mid A \in \mathcal{R}^U_{\mathcal{P}} \}.$$

The consequence relation \models is $\models_{3L}^{\lim wc}$, where $\mathcal{P} \models_{3L}^{\lim wc} F$ iff F is mapped to *true* under the least model of the weak completion of \mathcal{P} using the three-valued Łukasiewicz semantics. If the observation \mathcal{O} is a singleton set $\{L\}$, we simply write $\mathcal{O} = L$. A formula $F \in \mathcal{L}$ follows skeptically by abduction from \mathcal{P} and \mathcal{O} , in symbols $\mathcal{P}, \mathcal{O} \models_A^s F$, iff \mathcal{O} can be explained and for all minimal explanations \mathcal{E} we find $\mathcal{P} \cup \mathcal{E} \models_{3L}^{\lim wc} F$. A formula $F \in \mathcal{L}$ follows credulously by abduction from \mathcal{P} and \mathcal{O} , in symbols $\mathcal{P}, \mathcal{O} \models_A^c F$, iff there exists a minimal explanation \mathcal{E} for \mathcal{O} such that $\mathcal{P} \cup \mathcal{E} \models_{3L}^{\lim wc} F$.

5 Results

The Suppression Task Let us consider the experiments presented in the second column of Table 2. First, we will show that they can be adequately represented within the developed framework. To this end let

$$\begin{aligned} \mathcal{P}_e &= \{l \leftarrow e \land \neg ab, \ ab \leftarrow \bot\}, \\ \mathcal{P}_{et} &= \{l \leftarrow e \land \neg ab_1, \ ab_1 \leftarrow \bot, \ l \leftarrow t \land \neg ab_2, \\ ab_2 \leftarrow \bot\}, \\ \mathcal{P}_{eo} &= \{l \leftarrow e \land \neg ab_1, \ ab_1 \leftarrow \neg o, \ l \leftarrow o \land \neg ab_2, \\ ab_2 \leftarrow \neg e\} \end{aligned}$$

be the appropriate representation for C_e and C_e, C_t as well as C_e, C_o , respectively, obtained in the first step of the approach in (Stenning and van Lambalgen 2008).

- 1. Consider \mathcal{P}_e and let $\mathcal{O} = l$: $\mathcal{A} = \{e \leftarrow \top, e \leftarrow \bot\}$, $lm \ wc \ \mathcal{P}_e = \langle \emptyset, \{ab\} \rangle, \{e \leftarrow \top\}$ is the only minimal explanation for l, and $\mathcal{P}_e, l \models^s_A e$.
- 2. Consider \mathcal{P}_{et} and let $\mathcal{O} = l$: $\mathcal{A} = \{e \leftarrow \top, e \leftarrow \bot, t \leftarrow \top, t \leftarrow \bot\}$, $lm \ wc \ \mathcal{P}_{et} = \langle \emptyset, \{ab_1, ab_2\} \rangle, \{e \leftarrow \top\}$ and $\{t \leftarrow \top\}$ are the minimal explanations for l, and $\mathcal{P}_{et}, l \not\models_A^s e$.
- 3. Consider \mathcal{P}_{eo} and let $\mathcal{O} = l$: $\mathcal{A} = \{e \leftarrow \top, e \leftarrow \bot, o \leftarrow \top, o \leftarrow \bot\}$, $lm \ wc \ \mathcal{P}_{et} = \langle \emptyset, \emptyset \rangle, \{e \leftarrow \top, o \leftarrow \top\}$ is the only minimal explanation for l, and $\mathcal{P}_{eo}, l \models_A^s e$.
- Consider P_e and let O = ¬l: A = {e ← T, e ← ⊥}, *lm wc* P_e = ⟨∅, {ab}⟩, {e ← ⊥} is the only minimal explanation for ¬l, and P_e, ¬l ⊨^s_A ¬e.
- 5. Consider \mathcal{P}_{et} and let $\mathcal{O} = \neg l$: $\mathcal{A} = \{e \leftarrow \top, e \leftarrow \bot, t \leftarrow \top, t \leftarrow \bot\}$, $lm \ wc \ \mathcal{P}_{et} = \langle \emptyset, \{ab_1, ab_2\} \rangle, \{e \leftarrow \bot, t \leftarrow \bot\}$ is the only minimal explanation for $\neg l$, and $\mathcal{P}_{et}, \neg l \models_A^s \neg e$.

6. Consider \mathcal{P}_{eo} and let $\mathcal{O} = \neg l$: $\mathcal{A} = \{e \leftarrow \top, e \leftarrow \bot, o \leftarrow \top, o \leftarrow \bot\}$, $lm \ wc \ \mathcal{P}_{et} = \langle \emptyset, \emptyset \rangle, \{e \leftarrow \bot\}$ and $\{o \leftarrow \bot\}$ are minimal explanations for $\neg l$, and $\mathcal{P}_{eo}, \neg l \not\models_A^s \neg e$.

In other words, the formalization appears to be adequate with respect to the findings reported in (Byrne 1989).

Variations In this paragraph we discuss some examples which demonstrate that the various elements of the proposed formalization are needed. In (Hölldobler and Ramli 2009c; 2009b) it has already been shown that the strong three-valued Kleene logic with complete equivalence is inadequate to model all of the experiments mentioned in the first column of Table 2.

Reconsider the case of modus ponens with positive observation (case 1. above), but consider $\langle \mathcal{P}_e, \mathcal{A}, \models_{3L} \rangle$ instead of $\langle \mathcal{P}_e, \mathcal{A}, \models_{3L} \rangle$, where \models_{3L} is the usual entailment relation with respect to the three-valued Łukasiewicz logic. In such a logic least models may not exist. In this case, neither $\mathcal{P}_e \cup \{e \leftarrow \top\} \models_{3L} l \text{ nor } \mathcal{P}_e \cup \{e \leftarrow \bot\} \models_{3L} l \text{ because } ab$ can be mapped to *true*. Hence, the observation *l* can not be explained at all (in contrast to (Byrne 1989)). The example demonstrates that weak completion is needed.

Consider the case of modus ponens with negative observation (case 4. above), but consider now $\langle \mathcal{P}_e, \mathcal{A}, \models_{3\mathrm{L}}^c \rangle$ instead of $\langle \mathcal{P}_e, \mathcal{A}, \models_{3\mathrm{L}}^{\mathrm{lm\,wc}} \rangle$, where $\mathcal{P} \models_{3\mathrm{L}}^c F$ iff F holds in all models for the completion of \mathcal{P} . The completion of \mathcal{P}_e is $\{l \leftrightarrow e \land \neg ab, ab \leftrightarrow \bot, e \leftrightarrow \bot\}$, which entails $\neg l$, i.e. the empty set is an explanation. Hence, we find that $\mathcal{P}_e, \neg l \not\models_A^s \neg e$ (in contrast to (Byrne 1989)). The example demonstrates that completion is insufficient.

Reconsider again the case of modus ponens with negative observation (case 4. above), but weakly complete only the program \mathcal{P}_e and not the explanation. In this case we find that neither $wc \mathcal{P}_e$ nor $wc \mathcal{P}_e \cup \{e \leftarrow \top\}$ nor $wc \mathcal{P}_e \cup \{e \leftarrow \bot\}$ nor $wc \mathcal{P}_e \cup \{e \leftarrow \bot\}$ nor $wc \mathcal{P}_e \cup \{e \leftarrow \top, e \leftarrow \bot\}$ entails $\neg l$. Hence, the observation l cannot be explained (in contrast to (Byrne 1989)). The example demonstrates that explanations must be (weakly) completed as well.

Reconsider the case of alternative arguments with positive observation (case 2. above), but now reason credulously instead of skeptically. There are two minimal explanations, viz. $\{e \leftarrow \top\}$ as well as $\{e \leftarrow \bot\}$. Hence, $\mathcal{P}_{et}, l \not\models_A^s e$, but $\mathcal{P}_{et}, l \models_A^c e$. Credulous reasoning is inconsistent with (Byrne 1989).

Complexity Results The complexity classes of four abductive tasks are shown in Table 3: (1.) consistency, i.e. the question whether there exists a minimal explanation, (2.) relevance, i.e. the question whether there exists a minimal explanation containing a specific fact, (3.) necessity, i.e. whether all minimal explanations contain a specific fact, and (4.) the complexity of skeptical reasoning. Proofs of these results can be found in (Hölldobler, Philipp, and Wernhard 2010; Philipp 2010).

Consistency	NP-complete
Relevance	NP
Necessity	CONP-complete
Skeptical Reasoning	DP-complete

Table 3: Complexity classes of considered abductive tasks.

6 Conclusion

Logic appears to be adequate for human reasoning if weak completion, the three-valued Łukasiewicz semantics, the semantic operator $\Phi_{\mathcal{P}}^{SvL}$, and abduction are used. Human reasoning is modeled by, firstly, reasoning towards an appropriate logic program \mathcal{P} and, secondly, by reasoning with respect to the least model of the weak completion of the \mathcal{P} (which is equal to the least fixed point of $\Phi_{\mathcal{P}}^{SvL}$) and, in case of abduction, by taking a skeptical point of view. This approach matches data from studies in human reasoning and, in particular, the data first reported in (Byrne 1989). However, much remains to be done.

In (Hölldobler, Philipp, and Wernhard 2010) variations of some of the suppression task scenarios by Byrne are considered, where additional phrases like *she will not read a textbook in holidays; there are holidays* and *the library is not open in holidays; there are holidays* are included. In these extended scenarios, abduction with integrity constraints under the theoremhood as well as the consistency view (Kakas, Kowalski, and Toni 1993) yields plausible results, suggesting that corresponding experiments should be made.

There is a connectionist encoding of the approach (Hölldobler and Ramli 2009c) which, unfortunately, does not yet include abduction. On the other hand, various proposals to handle abduction in a connectionist setting have been made (e.g. (d'Avila Garcez et al. 2007)); these proposals are more or less straightforward encodings of a sequential search in the space of all possible explanations and they model only credulous reasoning. How do humans search for explanations? In which order are explanations generated by humans if there are several? Do humans prefer minimal explanations? Does attention play a role in the selection of explanations? Do humans reason skeptically or credulously?

In a Łukasiewicz logic the semantic deduction theorem does not hold. Is this adequate with respect to human reasoning? Likewise, in the three-valued Łukasiewicz logic an implication is mapped to *true* if both, its precondition and conclusion, are mapped to *unknown*. How do humans evaluate implications whose precondition and conclusion are mapped to *unknown*?

In the current approach negative and positive facts are not treated on the same level. Rather, by considering the weak completion of a program negative facts are dominated by positive information. How is negation treated in human reasoning?

In (Hölldobler and Ramli 2009a) it was shown that the semantic operator $\Phi_{\mathcal{P}}^{SvL}$ associated with a program \mathcal{P} (see Section 3) is a contraction if \mathcal{P} is acyclic. In this case, thanks to Banach's contraction mapping theorem, $\Phi_{\mathcal{P}}^{SvL}$ admits a unique fixed point which can be computed by iterating $\Phi_{\mathcal{P}}^{SvL}$ starting with an arbitrary initial interpretation. Do hu-

mans exhibit a behaviour which can be adequately modeled by contractional semantic operators? If so, can we generate appropriate level mappings (needed to show acyclicity of a program) by studying the behavior of humans?

Last but not least, what is the relation between the proposed approach and well-founded and/or stable and/or circumscription-projection (Wernhard 2010) semantics?

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