

Horn Belief Contraction: Remainders, Envelopes and Complexity*

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Abstract

A recent direction within belief revision theory is to develop a theory of belief change for the Horn knowledge representation framework. We consider questions related to the complexity aspects of previous work, leading to questions about Horn envelopes (or Horn LUB's), introduced earlier in the context of knowledge compilation.

A characterization is obtained of the remainders of a Horn belief set with respect to a consequence to be contracted, as the Horn envelopes of the belief set and an elementary conjunction corresponding to a truth assignment satisfying a certain *body building* formula. This gives an efficient algorithm to generate all remainders, each represented by a truth assignment. On the negative side, examples are given of Horn belief sets and consequences where Horn formulas representing the result of most contraction operators, based either on remainders or on weak remainders, must have *exponential size*.

Introduction

Belief revision deals with the question of how to update a set of beliefs when new information is obtained that may be inconsistent with the current beliefs (Hansson 1999; Peppas 2008). The standard approach is to formulate postulates that need to be satisfied by rational agents performing belief revision, such as the AGM postulates (Alchourrón, Gärdenfors, and Makinson 1985), and then to characterize all possible operations that satisfy these postulates. Until recently, work on AGM-style belief revision focused on logics at least as rich as full propositional logic, and assumed a language that was closed under the basic operations of propositional logic: negation, disjunction, and conjunction.

Evolving knowledge bases and ontologies appear to be interesting potential application areas for belief revision. These applications require tractable knowledge representation formalisms, such as Horn logic or many versions of description logic. The logic underlying these formalisms does not contain full propositional logic and thus it is of interest to develop a belief change theory for these logics, and, furthermore, for arbitrary logics in general.

In recent years, there have been a number of papers considering logics that are *not* necessarily closed under the basic operations. As far as we know, (Flouris, Plexousakis, and Antoniou 2004) (see also (Flouris 2006)) were the first to look into this question. Flouris et al. wanted to develop a theory of belief revision that would apply to description logic. In the case with closure under the basic propositional logic operators, a contraction operator obeying the AGM postulates always exists. This is not always the case for logics not so closed. Flouris et al. formulate a property called *decomposability* of the logic, and show that decomposability is a necessary and sufficient condition for the existence of an AGM-compliant belief contraction operator.

Starting in 2008, there has been a flurry of papers considering specifically the case of *belief contraction for Horn logic*, that is, the subset of propositional logic consisting of Horn formulas (Booth, Meyer, and Varzinczak 2009; Booth et al. 2010; Delgrande 2008; Delgrande and Wassermann 2010; Fotinopoulos and Papadopoulos 2009; Langlois et al. 2008; Zhuang and Pagnucco 2010; 2011).

Horn logic is a fragment of (propositional and predicate) logic which is of central importance in AI. Horn clauses express *rules* which are natural and easy to understand for humans. Another main reason for interest in Horn logic is that reasoning in propositional logic is computationally intractable, but reasoning in Horn logic is efficient.

(Langlois et al. 2008) apply the results of (Flouris, Plexousakis, and Antoniou 2004; Flouris 2006) to characterize for which Horn belief sets an AGM-compliant contraction operator exists, and give a *polynomial-time algorithm* to compute such a contraction when one exists. Their results are on the notion of a *complement* introduced by (Flouris, Plexousakis, and Antoniou 2004; Flouris 2006), which, in standard belief revision terms, is a remainder of a belief set with respect to itself.

The papers (Booth, Meyer, and Varzinczak 2009; Booth et al. 2010; Delgrande 2008; Delgrande and Wassermann 2010; Fotinopoulos and Papadopoulos 2009; Zhuang and Pagnucco 2010; 2011) ask the important question, “What sort of contraction operator should we use for the full Horn logic?” They consider variations of both the definition of remainder set and of how to combine remainder sets to obtain contraction operators that are defined for *all* Horn knowledge bases K and consequences φ , and give results relat-

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ing those contraction operators to various sets of postulates. A common feature is that the *recovery postulate*, which is assumed in (Flouris, Plexousakis, and Antoniou 2004; Flouris 2006), is replaced by others.

In this paper, we give some initial results about the complexity of computing some of those contractions and of related problems. Previous, mostly negative, complexity theoretic results on classical belief revision are given in (Eiter and Gottlob 1992; Liberatore 2000). It is important to point out that while one of the main motivations of considering Horn logic is to gain in efficiency, for example in reasoning with the belief set, it may be the case that one has to pay a price in the sense that some tasks become *more difficult* due to the restricted nature of the logic. Some of our results show that such a phenomenon does indeed occur.

Given a Horn belief set K and a Horn formula φ to be contracted, remainder sets can be formed by enlarging the set of truth assignments satisfying K by a single truth assignment falsifying φ . However, as noted in (Delgrande and Wassermann 2010), not all such truth assignments produce a remainder set, only those which, when intersected componentwise with the truth assignments satisfying K , do not produce any other truth assignments falsifying φ . Weak remainder sets are defined in (Delgrande and Wassermann 2010) similarly to remainder sets, except now an arbitrary truth assignment falsifying φ can be added to the satisfying truth assignments of K .

We give a logical characterization of those truth assignments which do lead to a remainder set, using a generalization of the *body building* formula from (Langlois et al. 2008).¹ Using this characterization, an efficient listing algorithm is given to list all such truth assignments. Thus, this algorithm produces all possible remainder sets, represented by their ‘generating’ truth assignment.

In the remainder of the paper we consider the question of finding a Horn formula representation for Horn belief sets produced by the various contraction operators. We construct Horn belief sets and Horn clause consequences to be contracted with the property that for certain contraction operators *every* Horn formula representing the new belief set must be exponentially larger than the original belief set. In fact, this holds for full meet contraction and, in an asymptotic sense, for most maxichoice and most partial meet contractions, both based on remainders and on weak remainders.² Our result is based on a new blow-up result for computing Horn envelopes (also called Horn LUB’s), which was obtained in connection with the study of *D-bases of closure systems* (Adaricheva and Nation 2011). (A related earlier blow-up result is given in (Kleine Büning and Lettmann 1987).) We also give some positive results on cases where such a blow-up cannot occur.

As it is indicated by the connection to bases of closure systems, Horn formulas are closely related to concepts in algebra (lattices, closure systems, closure operators and im-

¹In other words, an *efficiently computable syntactic criterion* is given to distinguish remainders from weak remainders.

²For our example, the two actually coincide as every weak remainder is a remainder.

plicational systems). There is a large body of work on problems related to the ones studied in this paper (Bertet and Monjardet 2010; Burosch, Demetrotics, and Katona 1987; Caspard and Monjardet 2003; Freese 1995) and the study of belief contraction for general logics in (Flouris, Plexousakis, and Antoniou 2004; Flouris 2006) also uses a lattice theoretic framework. We plan to give an account of these useful connections in the full version of this paper.

Proofs in the paper are either outlined or omitted due to lack of space.

Preliminaries

It is assumed that there is a fixed finite set of propositional variables. We use 0 and 1 for representing truth values. The set of truth assignments satisfying (resp., falsifying) a propositional formula ψ is denoted by $T(\psi)$ (resp., $F(\psi)$). For formulas ψ, φ it holds that $\psi \models \varphi$ (i.e., φ is a consequence of ψ) iff $T(\psi) \subseteq T(\varphi)$. For a truth assignment a and a variable x we sometimes write $x(a)$ for the value of the x -component of a .

Truth assignments are partially ordered by the relation $a \leq b$, which holds for $a = (a_1, \dots, a_n)$ and $b = (b_1, \dots, b_n)$ iff $a_i \leq b_i$ for every $i = 1, \dots, n$. We write $a < b$ if $a \leq b$ and $a \neq b$. The (componentwise) intersection of $a = (a_1, \dots, a_n)$ and $b = (b_1, \dots, b_n)$ is $a \wedge b = (a_1 \wedge b_1, \dots, a_n \wedge b_n)$.

The elementary conjunction C_a corresponding to a truth assignment a contains a variable (resp., the negation of a variable) iff the component corresponding to that variable in a is set to 1 (resp., 0). Thus, for example, $C_a = x_1 \wedge \bar{x}_2 \wedge x_3$ for $a = (1, 0, 1)$. Clearly $T(C_a) = \{a\}$.

A clause is a disjunction of literals (unnegated and negated variables). A clause is Horn if it contains at most one unnegated variable, and it is definite if it contains exactly one unnegated variable. (see, e.g., (Kleine Büning and Lettmann 1999) for background on Horn formulas). A definite Horn clause C is also written as $\text{Body}(C) \rightarrow \text{Head}(C)$, where $\text{Body}(C)$, resp., $\text{Head}(C)$, are the body, resp., the head of the clause. For example, the definite Horn clause $C = \bar{x} \vee \bar{y} \vee z$ can be written as $x, y \rightarrow z$, and $\text{Body}(C) = \{x, y\}$, $\text{Head}(C) = \{z\}$. A (definite) Horn formula is a conjunction of (definite) Horn clauses.

A clause C is an implicate of a formula ψ iff $\psi \models C$, and it is a prime implicate if none of its subclauses is an implicate. Every prime implicate of a (definite) Horn formula is a (definite) Horn clause. *Forward chaining* is an efficient procedure to decide $\psi \models C$, where ψ is a definite Horn formula and C is a definite Horn clause. It starts by marking all variables in the body of C . While there is a clause in ψ with all its body variables marked, the head variable of that clause is marked as well. Then $\psi \models C$ iff the head of C gets marked.

A Boolean function f can be represented by a Horn formula iff $T(f)$ is closed under intersection (Horn 1951; McKinsey 1943). Given an arbitrary propositional formula ψ , its Horn envelope $\text{Env}(\psi)$ is the conjunction of all Horn implicates of ψ . The Horn envelope is also referred to as the Horn LUB (least upper bound) or the Horn closure of ψ (Selman and Kautz 1996). Then it holds that $T(\text{Env}(\psi))$ is the closure of $T(\psi)$ under intersection.

The closure $\text{Cl}_\psi(V)$ of a set of variables V with respect to a definite Horn formula ψ is the set of all variables which must be true in every truth assignment satisfying ψ and having all variables in V set to 1, in other words

$$\text{Cl}_\psi(V) = \left\{ v : \psi \models \left(\bigwedge_{x \in V} x \rightarrow v \right) \right\} .$$

This is a closure operator on the set of all variables, which can also be computed by forward chaining. Note that $\text{Cl}_\psi(V)$ depends only on the function represented by ψ and not on the particular representation of ψ . This can also be seen by noting that closure consists of the variables set to 1 in the intersection of all satisfying truth assignments above the truth assignment that has exactly the variables in V set to 1.

A *Horn belief set* K is a set of *definite* Horn clauses closed under implication.³ As we are working with a fixed finite set of variables, belief sets are finite. A finite set of clauses in the belief set can be also thought of as the conjunction of the clauses in the set. For representational and computational purposes we may represent K by a subset of its clauses which imply all the others. Different logically equivalent formulas are considered to represent the *same* belief set. This is different from the *belief base* approach where clauses explicitly represented in the base have a distinguished role, and different logically equivalent representations are considered to be *different* as belief bases.

Body building: a characterization of remainders

If K is a Horn belief set and Horn formula φ is a consequence of K then a *remainder set* (or, briefly, a *remainder*) of K with respect to φ is a maximal subset $K' \subset K$ not implying φ .⁴ The set of all remainders of K with respect to φ is denoted by $K \downarrow \varphi$. The following proposition is implicit in (Delgrande and Wassermann 2010).

Proposition 1. $K \downarrow \varphi$ is equal to

$$\{ \text{Env}(K \vee C_a) : T(\text{Env}(K \vee C_a)) \cap F(\varphi) = \{a\} \} .$$

Proposition 1 means that the remainders of the belief set with respect to φ are obtained by picking a truth assignment a falsifying φ and forming the Horn envelope of the function obtained by adding the single new true point a to the belief set *assuming that the Horn envelope does not contain any additional false points of φ* .

Even though Proposition 1 gives a description of all remainders, it does not give an efficient algorithm to find any remainders as it does not tell how to find truth assignments a with the required property. In order to provide a constructive description let us introduce the following definition.

³In this paper we restrict our attention to definite Horn belief sets for simplicity. The extension of the results to the general case will be discussed in the final version.

⁴In the literature the term ‘remainder set’ is sometimes used for the set of all such sets (e.g., (Hansson 1999)).

Definition 2 (Body building formula).

$$K^\varphi = \bigwedge_{C \in \varphi} \bigwedge_{v \notin \text{Cl}_K(\text{Body}(C))} (\text{Body}(C), v \rightarrow \text{Head}(C)).$$

This definition generalizes the notion of a body building formula introduced in (Langlois et al. 2008). The definition in that paper corresponds to K^K in the current notation. Using Definition 2, remainders can be characterized as follows. (Due to lack of space we only include the proof of one direction.)

Theorem 3.

$$K \downarrow \varphi = \{ \text{Env}(K \vee C_a) : a \in T(K^\varphi) \cap F(\varphi) \} .$$

Proof. In order to prove the ‘ \subseteq ’ part of the theorem we show that if some $a \in F(\varphi)$ falsifies K^φ then

$$|T(\text{Env}(K \vee C_a)) \setminus T(\varphi)| \geq 2, \quad (1)$$

and thus by Proposition 1 it is not a remainder of K with respect to φ .

If $K^\varphi(a) = 0$ then there is a definite clause C in φ and a variable $v \notin \text{Cl}_K(\text{Body}(C))$ such that a falsifies $\text{Body}(C), v \rightarrow \text{Head}(C)$. Thus $\text{Body}(C)(a) = 1$, $v(a) = 1$ and $\text{Head}(C)(a) = 0$.

As $v \notin \text{Cl}_K(\text{Body}(C))$, there is a $b \in T(K)$ such that $\text{Body}(C)(b) = 1$ and $v(b) = 0$. But as $K \models \varphi$ and $b \in T(K)$, it holds that $b \in T(\varphi)$, and thus b must satisfy C . Hence $\text{Head}(C)(b) = 1$.

Now consider the truth assignment $d = a \wedge b$. Claim (1) follows if we show that $d \in T(\text{Env}(K \vee C_a)) \setminus T(\varphi)$ and $d \neq a$.

We know that $\text{Env}(K \vee C_a)$ is closed under intersection and so $b \in T(K)$ implies that $d \in T(\text{Env}(K \vee C_a))$. As $\text{Body}(C)(a) = \text{Body}(C)(b) = 1$ it follows that $\text{Body}(C)(d) = 1$. On the other hand, $\text{Head}(C)(a) = 0$ implies $\text{Head}(C)(d) = 0$. Thus d falsifies clause C and so it falsifies φ as well. Furthermore, $v(b) = 0$ implies $v(d) = 0$, thus from $v(a) = 1$ we get $a \neq d$. \square

It is claimed above that Theorem 3 can be used to find remainders. Indeed, a remainder can be obtained by finding a truth assignment $a \in T(K^\varphi) \cap F(\varphi)$. Such a truth assignment can be found by running an efficient Horn satisfiability algorithm on $K^\varphi \wedge \neg C$ for each clause C in φ . Actually, an even stronger statement is true: *all* remainders can be listed efficiently. As the number of remainders can be large, i.e., superpolynomial in the size of the belief set, we have to explain what is meant by efficient listing in general.

A *listing algorithm* (sometimes also called an enumeration algorithm) is an algorithm to produce a list of objects. For instance, a basic task in data mining is to produce a list of potentially ‘interesting’ association rules in a transaction database, for some specific definition of interestingness. Using this list, the user is supposed to select those rules which are found to be truly interesting. For belief change, such algorithms could be used to produce a list of possible results of contraction operators, again, letting the user decide which one is preferred. Another possible application is in the experimental study of belief change algorithms, suggested in

the last section as a topic for further research, where a list of possible contractions could be necessary to compute various statistics.

Different efficiency criteria for listing algorithms are described in (Goldberg 1993; Johnson, Yannakakis, and Papadimitriou 1988). Here we only define listing with polynomial delay. An algorithm listing a set of objects works with *polynomial delay* if the time spent before outputting the first object and the time spent between outputting two successive objects (and between the final output and termination) is bounded by a polynomial function of the input size.

Theorem 4. *There is a polynomial delay algorithm which, given a Horn belief set K and a consequence φ of K , outputs a list of all truth assignments a such that $\text{Env}(K \vee C_a)$ is in $K \downarrow \varphi$.*

The algorithm does backtracking for subproblems obtained by restricting variables to constants, and it uses Horn satisfiability to check whether a new subtree contains any remainders.

Note that the algorithm in Theorem 4 produces a list of all remainders, where each remainder is *represented by a truth assignment*, and not by a Horn formula for $\text{Env}(K \vee C_a)$. This begs the question, considered in the next section, whether Horn formulas for $\text{Env}(K \vee C_a)$ can be computed efficiently?

Horn envelopes

As Proposition 1 shows, remainders are closely related to Horn envelopes, introduced by (Selman and Kautz 1996) in the context of knowledge compilation. It was shown in (Selman and Kautz 1996) that Horn envelopes can blow up in size or can be hard to compute. We have studied the computational aspects of Horn envelopes recently in (Langlois, Sloan, and Turán 2009). The special case of computing the Horn envelope of the disjunction of two Horn formulas has been considered in (Eiter, Ibaraki, and Makino 2001; Eiter and Makino 2008). They showed negative results analogous to the general case. Proposition 1 suggests considering the special case where one of the Horn formulas is an elementary conjunction, i.e., it is satisfied by a single truth assignment.

Definition 5 (Singleton Horn Extension (SHE) problem). *Given a definite Horn belief set K and a truth assignment a falsifying K , compute the Horn envelope $\text{Env}(K \vee C_a)$.*

We formulate a simple proposition concerning envelopes of disjunctions.

Proposition 6. *Let ψ_1, ψ_2 be arbitrary formulas and let Horn clause C be a prime implicate of ψ_1 and an implicate of ψ_2 . Then C is a prime implicate of $\text{Env}(\psi_1 \vee \psi_2)$.*

Later in this section we show that the SHE problem is intractable in general, as it may be the case that every Horn formula representing the output must be exponentially large compared to the input size. This negative result does not depend on any unproven complexity theoretic assumptions. On the other hand, it assumes that the output has to be represented as a Horn formula. In view of the negative result

it is of interest to identify cases where the problem has an efficient solution. We begin with such positive results.

Positive results

The following proposition shows that $\text{Env}(K \vee C_a)$ has an explicit description in terms of the prime implicates of K . Let $PI(K)$ denote the set of prime implicates of K , and $PI^1(K, a)$, resp., $PI^0(K, a)$ be the set of prime implicates of K satisfied, resp., falsified by a . We write $a = (a_1, \dots, a_n)$ and $x^1 = x, x^0 = \bar{x}$.

Proposition 7. *$\text{Env}(K \vee C_a)$ can be written as*

$$\left(\bigwedge_{C \in PI^1(K, a)} C \right) \wedge \left(\bigwedge_{C \in PI^0(K, a) \{i: x_i(a)=0\}} (C \vee \bar{x}_i) \right).$$

Proof. We show that $\text{Env}(K \vee C_a)$ is logically equivalent to

$$\bigwedge_{C \in PI(K), C \vee x_i^{a_i} \text{ definite}} (C \vee x_i^{a_i}). \quad (2)$$

This, then, can be rewritten in the form stated in the proposition. The ‘ \models ’ direction follows by noting that by distributivity, every clause in (2) is a Horn implicate of $K \vee C_a$, and thus it is an implicate of $\text{Env}(K \vee C_a)$. For the other direction, consider a Horn prime implicate D of $K \vee C_a$. Then D is an implicate of K . Let $D' \subseteq D$ be a prime implicate of K . As $C_a(a) = 1$, it holds that $D(a) = 1$ and so D contains a literal $x_i^{a_i}$. But then $D' \vee x_i^{a_i}$ occurs in (2), and so D is an implicate of (2). \square

Proposition 7 does *not* lead to an efficient algorithm for computing $\text{Env}(K \vee C_a)$ in general, as K can have exponentially many prime implicates compared to its size. An example is given in (Khardon 1995), and a similar example is given in the next subsection. Nevertheless, one can draw positive algorithmic consequences, and we formulate two of those. We use the fact that the prime implicates of a Horn formula can be listed efficiently (Boros, Crama, and Hammer 1990).

Corollary 8. *The SHE problem can be solved in time polynomial in the size of K and the number of prime implicates of K .*

Proof. The algorithm first runs Boros et al.’s algorithm to generate the prime implicates of K and then uses Proposition 7 to produce $\text{Env}(K \vee C_a)$. \square

Corollary 8 provides efficient algorithms for any class of belief sets with small number of prime implicates. One such class is quadratic Horn formulas. A definite Horn formula is *quadratic* if its clauses are of size two, i.e., they are of the form $a \rightarrow b$.

Corollary 9. *The SHE problem can be solved efficiently for quadratic belief sets K .*

Proof. Resolution of size two clauses is again of size two, and hence an n -variable quadratic belief set has $O(n^2)$ prime implicates. \square

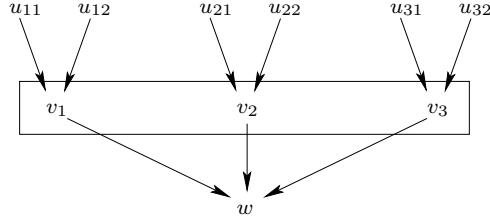


Figure 1: The belief set K_3

Quadratic Horn formulas are one of the tractable subclasses of Horn formulas for problems which are hard for Horn formulas in general, such as minimization. The other tractable class is acyclic formulas: a definite Horn formula is *acyclic* if the directed graph over the set of variables, obtained by adding a directed edge from every body variable to the head variable, has no directed cycles (Boros et al. 2010). It is tempting to conjecture that the SHE problem might also be tractable for acyclic formulas. The next subsection shows that this is not the case.

Variants of Proposition 7 can be formulated for formulas over other sets of clauses satisfying some general conditions, along the lines of (del Val 2005). This may be of interest for belief change over other restricted logics.

A negative result

Consider variables $u_{i,j}, v_i$ and w , where $1 \leq i \leq n, 1 \leq j \leq 2$, and let the Horn belief set K_n be given by the $2n + 1$ Horn clauses

$$u_{i,j} \rightarrow v_i, \quad 1 \leq i \leq n, 1 \leq j \leq 2$$

and

$$v_1, \dots, v_n \rightarrow w.$$

The belief set K_3 is shown in Figure 1. Note that K_n is acyclic. Furthermore, let a_n be the truth assignment setting all u -variables to 1, all v -variables to 0 and w to 1. Clearly a_n falsifies K_n .

Now we turn to the negative result.

Theorem 10. *Every Horn formula representing $\text{Env}(K_n \vee C_{a_n})$ has at least 2^n clauses.*

We prove a stronger statement which will be used in the next section in the discussion of partial meet contractions.

Let A be a set of truth assignments to the variables $u_{i,j}, v_i$ and w (where $1 \leq i \leq n, 1 \leq j \leq 2$) such that in every $a \in A$ the u -variables and w are set to 1 and v_1 is set to 0. Assume, furthermore, that there are altogether $k \geq 1$ variables which are set to 0 in at least one $a \in A$. It can be assumed *w.l.o.g.* that these variables are v_1, \dots, v_k .

Theorem 11. *Every Horn formula representing*

$$\text{Env} \left(K_n \vee \bigvee_{a \in A} C_a \right)$$

contains at least 2^k clauses.

Proof. Let χ be a Horn formula representing $\text{Env}(K_n \vee \bigvee_{a \in A} C_a)$. Note that K_n is definite, so it is satisfied by the all ones vector. Thus χ is also satisfied by the all ones vector and so it is definite as well.

For every $s = (s_1, \dots, s_k)$ such that $1 \leq s_i \leq 2$ for $i = 1, \dots, k$ consider the clause

$$\psi_s = (u_{1,s_1}, \dots, u_{k,s_k}, v_{k+1}, \dots, v_n \rightarrow w).$$

The theorem follows if we show that χ contains ψ_s .

The clause ψ_s is an implicate of K_n , as after marking its body variables, we can mark v_1, \dots, v_k and then we can mark w . Also, ψ_s is satisfied by all $a \in A$. Thus ψ_s is an implicate of χ as well.

It also holds that ψ_s is a prime implicate of K_n . Indeed, if $C' = \psi_s \setminus \{u_{i,s_i}\}$ for some $1 \leq i \leq k$, or if $C' = \psi_s \setminus \{v_i\}$ for some $k+1 \leq i \leq n$, then the truth assignment setting $u_{i,1}, u_{i,2}, v_i$ and w to 0, and setting all other variables to 1, satisfies K_n and falsifies C' . If $C' = \psi_s \setminus \{w\}$ then the all ones truth assignment satisfies K_n and falsifies C' .

Let b be the truth assignment for which every body variable in ψ_s is set to 1 and all other variables are set to 0. As b falsifies ψ_s , it also falsifies χ , and so there is a clause C in χ such that $C(b) = 0$. Thus it must be the case that

$$\text{Body}(C) \subseteq \{u_{1,s_1}, \dots, u_{k,s_k}, v_{k+1}, \dots, v_n\}.$$

Furthermore, C is an implicate of K_n thus its head is in

$$\text{Cl}_{K_n}(\text{Body}(C)) \setminus \text{Body}(C) \subseteq \{v_1, \dots, v_k, w\}.$$

Now C is satisfied by every $a \in A$. But every $a \in A$ satisfies the body of C , and every $v_i (1 \leq i \leq k)$ is falsified by some $a \in A$. So the head of C cannot be a v -variable and thus it must be w . So C must be a subclause of ψ_s , and as ψ_s was shown to be a prime implicate of K_n , it must be equal to ψ_s . \square

A remark on characteristic models

For every Horn formula ψ the set $T(\psi)$ of satisfying truth assignments is closed under intersection. Those satisfying truth assignments which cannot be obtained as the intersection of others are called the *characteristic models* or *characteristic vectors* of ψ (Kautz, Kearns, and Selman 1995; Khardon and Roth 1996). Representing a Horn function by its set of characteristic vectors is an alternative to the standard clausal representation. This representation has various advantages and disadvantages. The clausal and characteristic set representations are incomparable in the sense that

there are examples where one has polynomial size and the other has exponential size (Khardon and Roth 1996).

Possible connections of characteristic models to Horn belief contraction are discussed in (Delgrande and Wassermann 2010). Let us assume that the Horn belief set K is represented by its set of characteristic vectors $\text{Char}(K)$. Then every truth assignment $b \in T(K \vee C_a)$ is obtained as an intersection of vectors in $\text{Char}(K) \cup \{a\}$, hence $\text{Char}(K \vee C_a) \subseteq \text{Char}(K) \cup \{a\}$. The set $\text{Char}(K \vee C_a)$ can be found efficiently by eliminating those vectors from $\text{Char}(K) \cup \{a\}$ which can be obtained as the intersection of vectors above them in the set.

In view of the negative results of the previous section one may ask whether $\text{Env}(K \vee C_a)$ has a short Horn formula representation if, in addition, it holds that $\text{Char}(K)$ is small. Unfortunately, this is not the case as the characteristic set of the belief set K_n considered above turns out to be small.

Proposition 12.

$$|\text{Char}(K_n)| = \Theta(n).$$

Proof. The characteristic models are the following: those with a single $u_{i,j} = 0$ and all other variables set to 1, those with $u_{i,1} = u_{i,2} = v_i = w = 0$ for a single i and all other variables set to 1, and those with $u_{i,1} = u_{i,2} = v_i = 0$ for a single i and all other variables set to 1. \square

Complexity of Horn belief contraction

In this section we draw conclusions from Theorem 11 for Horn belief contraction.

A *partial meet contraction* $K \dot{-} \varphi$ is an intersection of remainders, thus by Theorem 3 it is of the form

$$\text{Env} \left(K \vee \bigvee_{a \in A} C_a \right), \quad (3)$$

where

$$A \subseteq T(K^\varphi) \cap F(\varphi). \quad (4)$$

A *maxichoice contraction* corresponds to a singleton subset in (4) and *full meet contraction* corresponds to equality in (4).

If K is a Horn belief set and Horn formula φ is a consequence of K then a *weak remainder* is a belief set of the form $\text{Env}(K \vee C_a)$ for any $a \in F(\varphi)$ and so the set of weak remainders is

$$K \Downarrow \varphi = \{\text{Env}(K \vee C_a) : a \in F(\varphi)\}.$$

A *partial meet contraction based on weak remainders* $K \dot{-}_w \varphi$ is of the form (3) where

$$A \subseteq F(\varphi). \quad (5)$$

A *maxichoice contraction based on weak remainders* corresponds to a singleton subset in (5) and *full meet contraction based on weak remainders* corresponds to equality in (5).

In order to make use of Theorem 11 in the context of contractions we also need to specify a consequence to be contracted.

Let the implicate φ_n to be contracted from K_n be

$$u_{1,1}, \dots, u_{i,j}, \dots, u_{n,2}, w \rightarrow v_1.$$

It is clear that φ_n is an implicate as after marking $u_{1,1}$ we can already mark v_1 .

Proposition 13.

$$K_n \downarrow \varphi_n = K_n \Downarrow \varphi_n = \{\text{Env}(K_n \vee C_a) : a \in F(\varphi_n)\}$$

Proof. This follows from Theorem 3 noting that $\text{Cl}_{K_n}(\text{Body}(\varphi_n))$ is the set of all variables, thus the body building formula K^φ is the empty conjunction, and so it is identically true. \square

In the following theorem a size lower bound is said to hold for *almost all* contractions if the fraction of contractions with at least that size approaches 1 as n grows.

Theorem 14. *Let us consider contractions, or weak remainder based contractions of the consequence φ_n from the belief set K_n .*

a) *Every Horn formula representation of the full meet contraction contains at least 2^n clauses.*

b) *For every $\epsilon > 0$ and for almost all maxichoice contractions, every Horn representation contains at least $2^{((1/2)-\epsilon)n}$ clauses.*

c) *For almost all partial meet contractions, every Horn representation contains at least 2^n clauses.*

Further remarks

We have shown that every Horn representation of the full meet contraction, and most maxichoice and partial meet contractions of the belief set K_n with respect to its consequence φ_n must be exponentially large. This belief set is simple and natural in the sense that it can be thought of as consisting of observable propositions $u_{i,j}$, intermediate conclusions (hidden nodes?) v_i and a final conclusion w , where each $u_{i,j}$ is sufficient to cause v_i and all v_i 's are necessary to cause w . The fact that contractions of such a simple belief set may blow up in size may indicate that this phenomenon occurs more often than just for an artificially constructed pathological example. It would be interesting to perform experiments exploring this. More generally, it would be of interest to gather computational experience about various other aspects of Horn belief contractions (some initial results are given in (Langlois et al. 2008)).

In view of the fact that fully AGM-compliant Horn-contractions do not exist in the sense of (Flouris, Plexousakis, and Antoniou 2004; Flouris 2006) it was suggested in (Langlois et al. 2008) that one might study the possibilities of *approximating* them. The negative results in the current paper give a different motivation for such an approach: when the result of a contraction is too large, approximate it with a smaller one. This may be related to *anytime* belief revision algorithms (Williams 1997).

The results of this paper also suggest several specific questions for further study, such as considering the complexity of infra-remainders (Booth, Meyer, and Varzinczak 2009) and package contraction (Delgrande and Wassermann 2010), and proving complexity-theoretic hardness results for the SHE problem analogous to the results of (Eiter and Makino 2008).

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